

**AMENDMENTS TO THE CLAIMS**

1. (Previously presented) A method for processing signal values in a digital signal processor, comprising the steps of:  
in response to a single trellis instruction that specifies trellis state metrics for a time  $t_0$ , based on the signal values, and transition metrics from time  $t_0$  to time  $t_1$ , for selected trellis states:  
adding a transition metric to a first state metric for time  $t_0$  to provide a first value;  
subtracting the transition metric from a second state metric for time  $t_0$  to provide a second value;  
for each selected trellis state, comparing the first and second values; and  
selecting the maximum of the first and second values for each selected trellis state to provide trellis state metrics for time  $t_1$ , wherein the adding, subtracting, comparing and selecting operations of the single trellis instruction are executed by the digital signal processor in a single clock cycle of the digital signal processor.
2. (Previously presented) A method as defined in claim 1, further comprising the step of, for each selected trellis state, adding to the maximum value a correction factor that is a function of the first and second values.
3. (Original) A method as defined in claim 2, wherein the step of adding a correction factor comprises accessing a lookup table containing correction factors.
4. (Original) A method as defined in claim 1, wherein the trellis instruction implements a forward trellis function for calculating  $\alpha$  trellis state metrics.
5. (Original) A method as defined in claim 1, wherein the trellis instruction implements a reverse trellis function for calculating  $\beta$  trellis state metrics.

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6. (Original) A method as defined in claim 1, wherein the trellis instruction simultaneously implements a forward trellis function for calculating  $\alpha$  trellis state metrics and a reverse trellis function for calculating  $\beta$  trellis state metrics, using a single instruction, multiple data approach.

7.-17. (Canceled)

18. (Previously presented) A processor for processing signal values, comprising:  
a memory for storing instructions and operands for digital signal computations;  
a program sequencer for generating instruction addresses for fetching selected ones of said instructions from said memory; and  
a computation block comprising a register file for temporary storage of operands and results and an accelerator for executing a trellis instruction that specifies trellis state metrics for a time  $t_0$  and transition metrics from time  $t_0$  to time  $t_1$ , wherein the trellis state metrics are based on the signal values, said accelerator comprising an adder for adding a transition metric to a first state metric for time  $t_0$  to provide a first value, an adder for subtracting the transition metric from a second state metric for time  $t_0$  to provide a second value, a comparator for determining the maximum of the first and second values for each trellis state and a data selector for selecting the maximum of the first and second values for selected trellis states, wherein the adders, the comparator and the data selector of the accelerator are configured to execute the adding, subtracting, comparing and selecting operations of the trellis instruction in a single clock cycle of the processor.

19.-24. (Canceled)

25. (Previously presented) A processor as defined in claim 18, wherein the accelerator includes an additional adder to add to the maximum of the first and second values a correction factor that is a function of the first and second values.

26. (Previously presented) A processor as defined in claim 25, wherein the accelerator further comprises a lookup table containing correction factors.

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